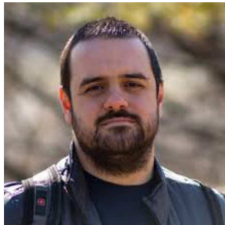


Workshop on Data Science - Emap/FGV

Spatio-Temporal Data Analytics via Graph Signal Processing

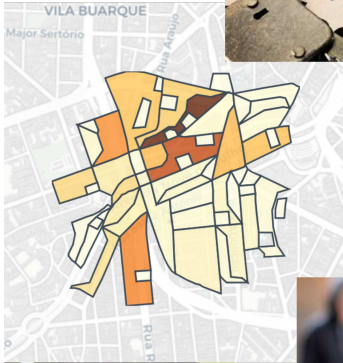
Prof. Luis Gustavo Nonato
University of São Paulo - Brazil

Joint Work With



What is spatio-temporal data and why to understand it?

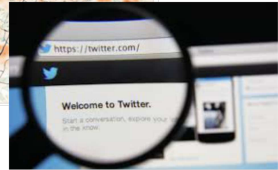
Spatio-Temporal Data Analysis



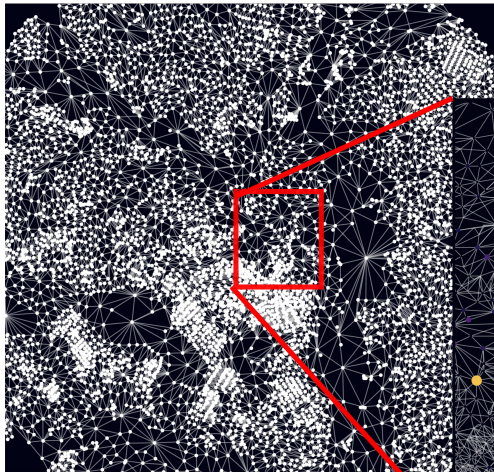
Spatio-Temporal Data Analysis



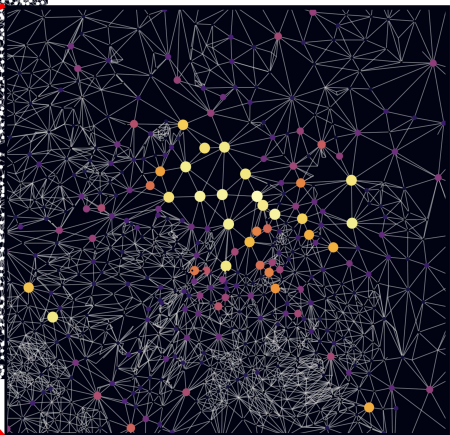
Spatio-Temporal Data Analysis



Graph



Time-varying Signal



Graph Signals Processing

How to analyze signals defined on graphs so as to uncover phenomena and identify patterns hidden in the data?

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Graph Signal Processing (GSP) has emerged as a main alternative in this context.

The main idea of GSP is to adapt well established signal processing tools such as Linear Filtering, Fourier, and Wavelet transforms to the context of graphs.

Basic Concepts and Notation

The Graph Laplacian

The Graph Laplacian

A undirected weighted graph $G = (V, E, W)$ is defined by a set of nodes $V = \{\tau_i\}$, edges $E = \{e_{ij}\}$ linking pairs of nodes τ_i and τ_j , and a symmetric weight matrix W whose entries satisfies

$$\begin{cases} w_{ij} > 0 & \text{if } \exists e_{ij} \in E \\ w_{ij} = 0 & \text{otherwise} \end{cases}$$

w_{ij} indicates how strongly the nodes τ_i and τ_j are linked.

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Graph Laplacian

$$L = D - W$$

where D is a diagonal matrix with entries $d_{ii} = \sum_j w_{ij}$.

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L is a symmetric positive semidefinite matrix.

Spectral Decomposition

Eigenvectors of L

$$\underbrace{\begin{bmatrix} \vdots & \vdots & & \vdots \\ u_1 & u_2 & \cdots & u_n \\ \vdots & \vdots & & \vdots \end{bmatrix}}_U$$

Eigenvalues of L

$$\underbrace{\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}}_\Lambda$$

$$L = U\Lambda U^\top$$

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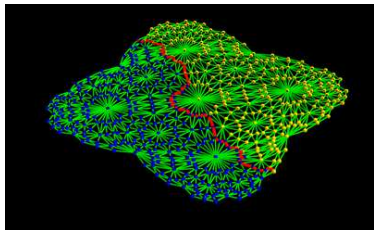
$$0 = \lambda_1 \leq \lambda_2 \leq \cdots \leq \lambda_n$$

Eigenvectors are function defined on the vertices of G

$$u_i : V \rightarrow \mathbb{R}$$

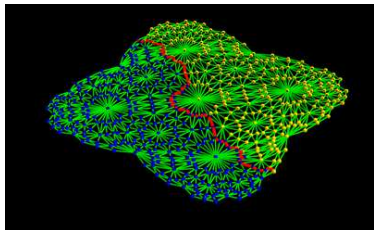
The *Discrete Courant's Nodal Theorem*

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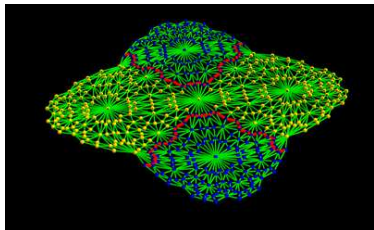


u_2

The *Discrete Courant's Nodal Theorem*

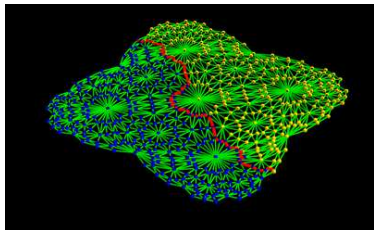


u_2

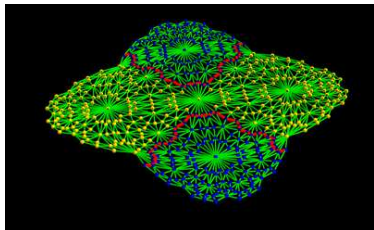


u_4

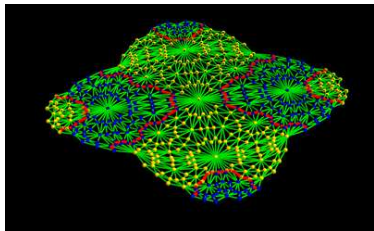
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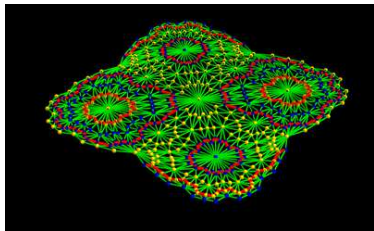
u_2



u_4



u_9



u_{11}

Eigenvectors of the graph Laplacian behaves similarly to Fourier basis, tending to increase oscillation as the corresponding eigenvalue increases.

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$$\lambda_l \longrightarrow \text{frequencies}$$

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$\lambda_l \longrightarrow$ frequencies

$u_l \longrightarrow$ basis function

Graph Fourier Transform

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Given a function $f : V \rightarrow \mathbb{R}$ defined on the vertices of G :

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Graph Fourier Transform (GFT)

The Graph Fourier Transform of f is defined as

$$GFT[f](\lambda_l) = \hat{f}(\lambda_l) = \langle f, u_l \rangle = \sum_{i=1}^n f(i)u_l(i) \rightarrow \boxed{\hat{f} = U^T f}$$

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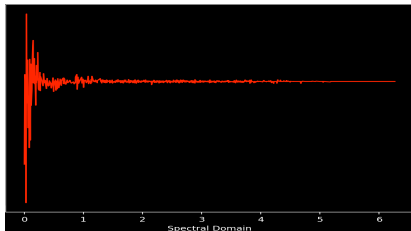
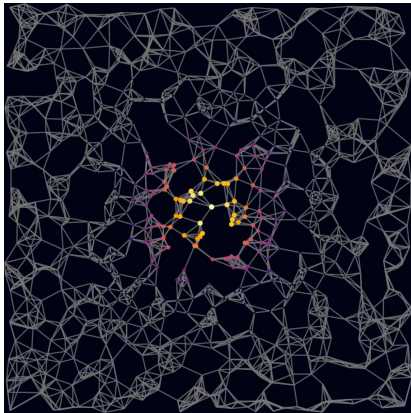
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Inverse Graph Fourier Transform

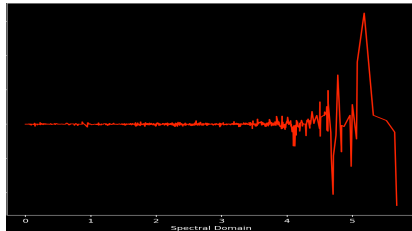
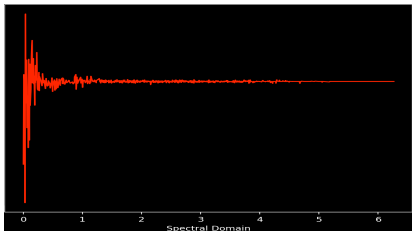
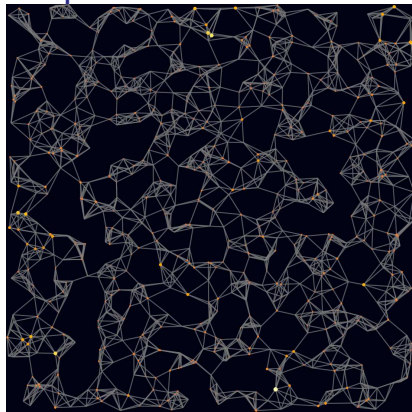
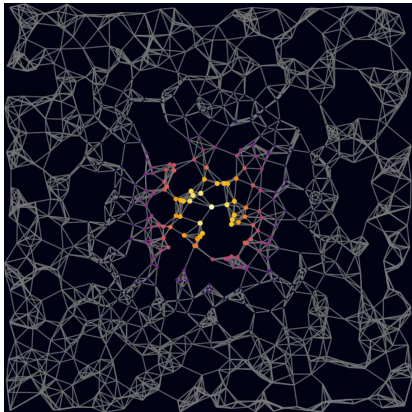
The Inverse Graph Fourier Transform is given by

$$iGFT[\hat{f}](i) = f(i) = \sum_{l=0}^{n-1} \hat{f}(\lambda_l) u_l(i) \rightarrow \boxed{f = U \hat{f}}$$

Graph Fourier Transform



Graph Fourier Transform



Filtering Signals on Graphs

Classical Filtering and Convolution

Convolution

$$(f * g)(x) = \int_{-\infty}^{\infty} f(x-t)g(t)dt$$

$$\mathcal{F}[f * g] = \hat{f} \cdot \hat{g}$$

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Linear Time Invariant Filter

If \mathcal{L} is a linear time invariant filter then there exists a function h such that

$$\mathcal{L}[f] = f * h$$

Graph Convolution

The definition of convolution can not be directly applied to graphs because the shift operation $f(x - t)$ is not well defined on the graph domain.

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$$(f * g)(i) = \sum_{l=1}^n \hat{f}(\lambda_l) \hat{g}(\lambda_l) u_l(i)$$

Graph Spectral Filtering

$$\mathcal{L}[f] = iGFT[\hat{f} \cdot \hat{h}]$$

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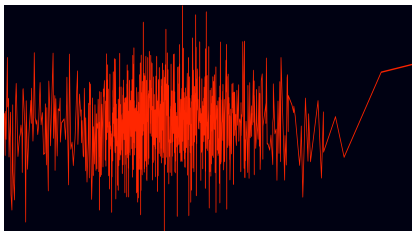
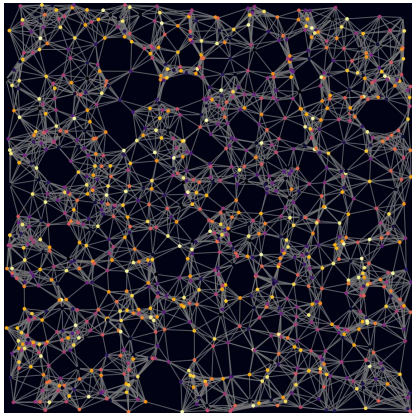
$$\mathcal{L}[f] = \hat{h}(L)f$$

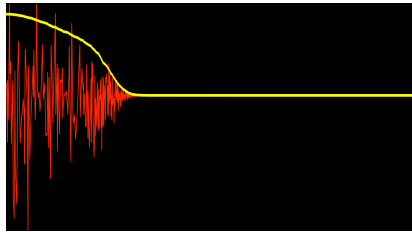
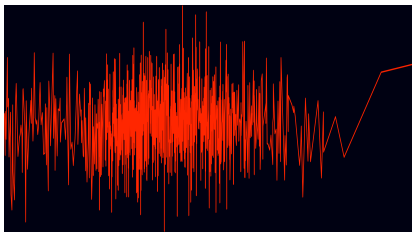
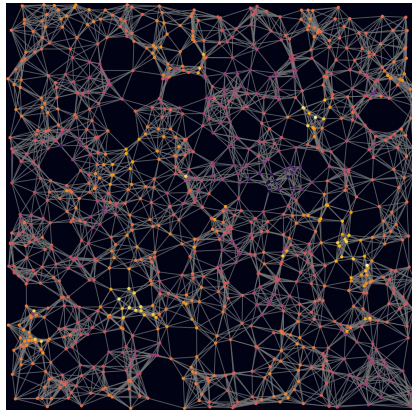
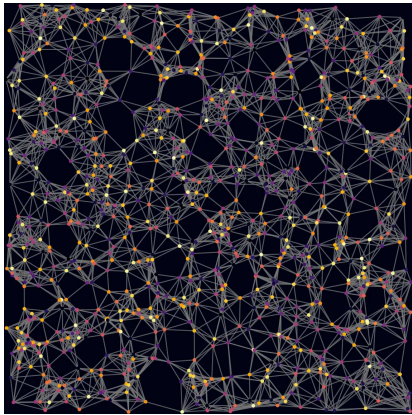
Graph Spectral Filtering

$$\mathcal{L}[f] = iGFT[\hat{f} \cdot \hat{h}]$$

$$\mathcal{L}[f] = \hat{h}(L)f$$

$$\mathcal{L}[f] = U \begin{bmatrix} \hat{h}(\lambda_1) & & \\ & \ddots & \\ & & \hat{h}(\lambda_n) \end{bmatrix} U^\top f$$





Filter Design

Graph Spectral Filtering: Smoothing

The design of filters with specific properties is a central issue.

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Smoothing a function f :

Find h such that $g = \mathcal{L}[f] = \hat{h}(L)f$ minimizes

$$\arg \min_h \{ \|f - g\|^2 + \gamma g^\top L g \}$$

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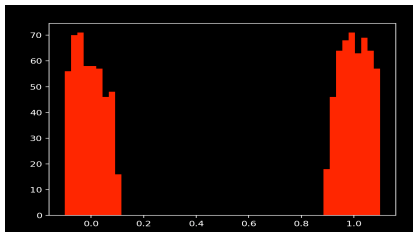
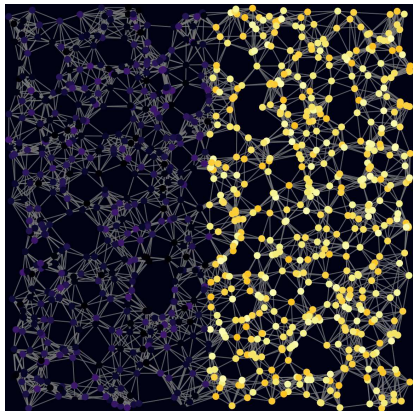
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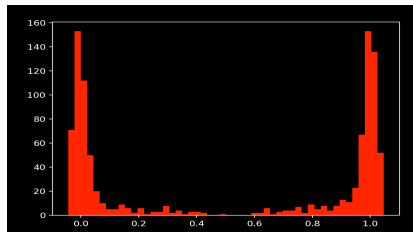
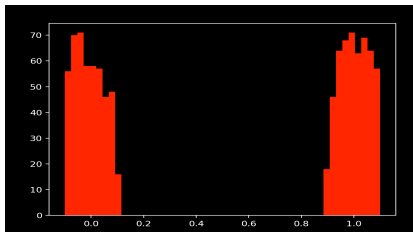
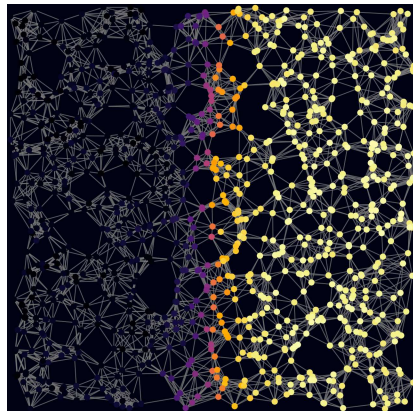
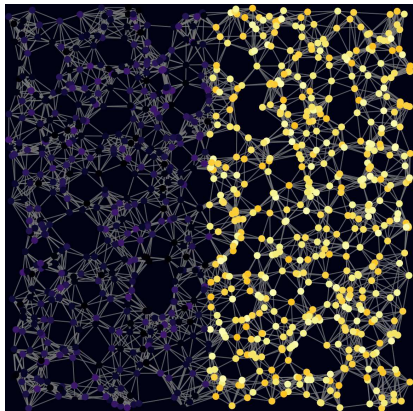
$$\arg \min_h \{ \|f - g\|^2 + \gamma g^\top L g \}$$

It can be shown that

$$\hat{h}(\lambda) = \frac{1}{1 + \gamma \lambda}$$

is the sought solution.



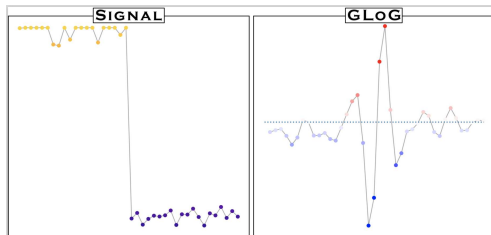


Graph Spectral Filtering: GLoG

Laplacian of Gaussian (LoG)

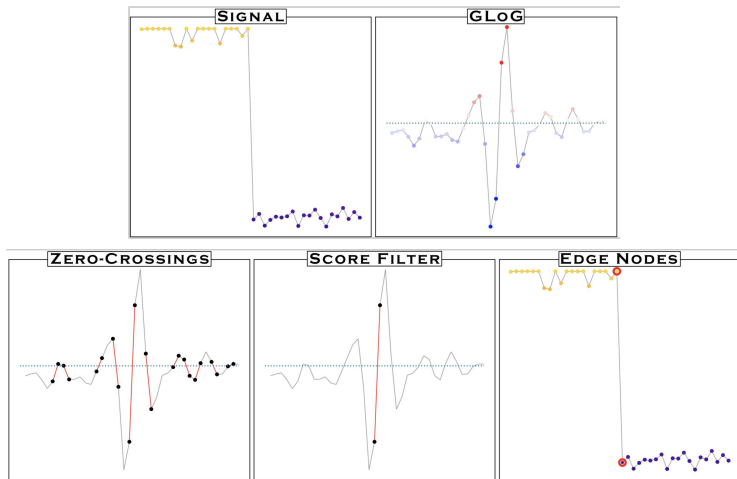
Graph Spectral Filtering: GLoG

Laplacian of Gaussian (LoG)



Graph Spectral Filtering: GLoG

Laplacian of Gaussian (LoG)



$$\text{LoG}(f) = \nabla^2[G * f], \quad G \text{ is a Gaussian function}$$

Graph Spectral Filtering: GLoG

Laplacian of Gaussian (LoG)

In the context of GSP, the goal is to define h such that

$$GLoG(f) = \hat{h}(L)f$$

Graph Spectral Filtering: GLoG

Laplacian of Gaussian (LoG)

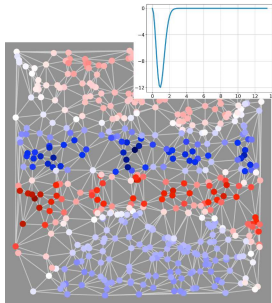
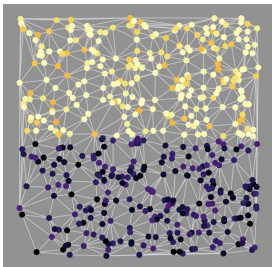
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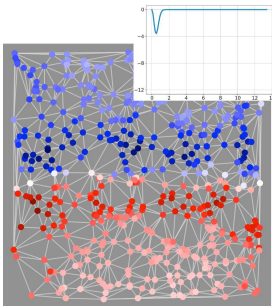
The solution is given by

$$\hat{h}(\lambda_l) = -4\pi^2\lambda_l^2 \exp(\sigma^2\lambda_l^2/2)$$

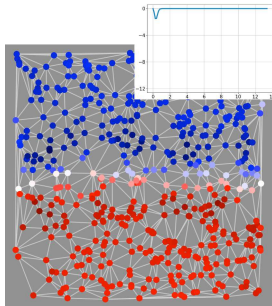
In the 2D case, the *GLoG* is equivalent to the *LoG* filter.



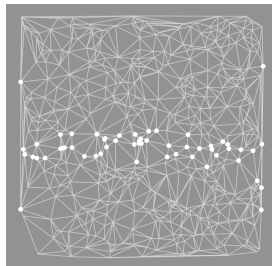
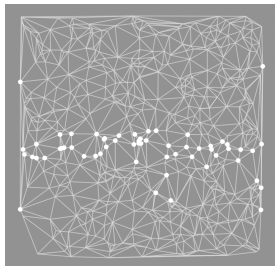
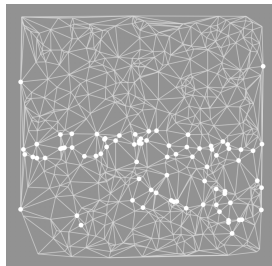
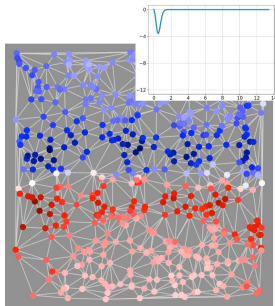
$\sigma = 1$



$\sigma = 2$



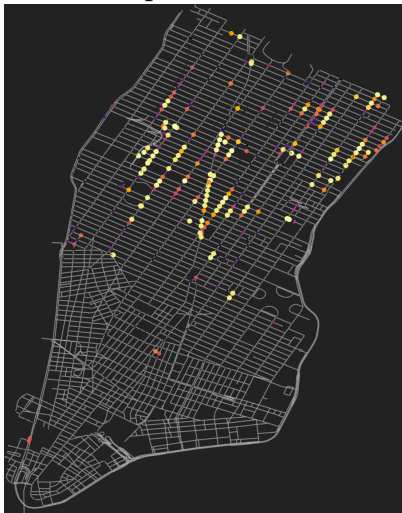
$\sigma = 3$



Taxi Pick ups in Downtown Manhattan

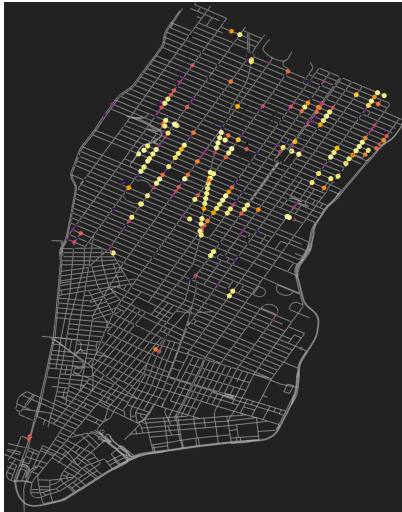


Taxi Pick ups in Downtown Manhattan



Visual Enhancement

Taxi Pick ups in Downtown Manhattan



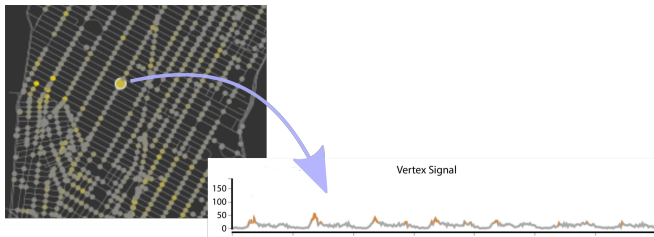
Spatio-Temporal Data Analysis via GLoG

Spatio-Temporal Data Analysis

$$f : V \times T \rightarrow \mathbb{R}, \quad T = \{t_1, t_2, \dots, t_m\}$$

Spatio-Temporal Data Analysis

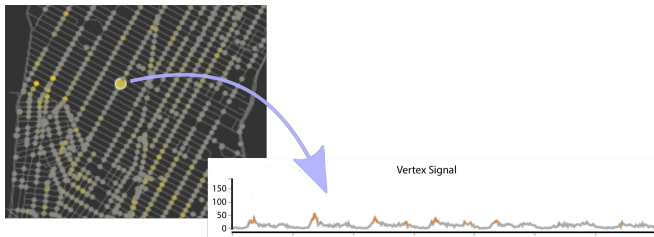
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Edge nodes: adjacent nodes where GLoG changes sign

Spatio-Temporal Data Analysis

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Edge nodes: adjacent nodes where GLoG changes sign
Probability of edge nodes

$$I(\tau_i, t_k) = \begin{cases} 1 & \text{if } \tau_i \text{ is an edge node in time slice } t_k \\ 0 & \text{otherwise} \end{cases}$$

$$p_e(\tau_i) = \frac{1}{m} \sum_{k=1}^m I(\tau_i, t_k)$$

Spatio-Temporal Data Analysis

Probability of an observed node configuration:

$$p(I(\tau_i, t_k)) = \begin{cases} p_e(\tau_i) & \text{if } I(\tau_i, t_k) = 1 \\ 1 - p_e(\tau_i) & \text{if } I(\tau_i, t_k) = 0 \end{cases}$$

Spatio-Temporal Data Analysis

Probability of an observed node configuration:

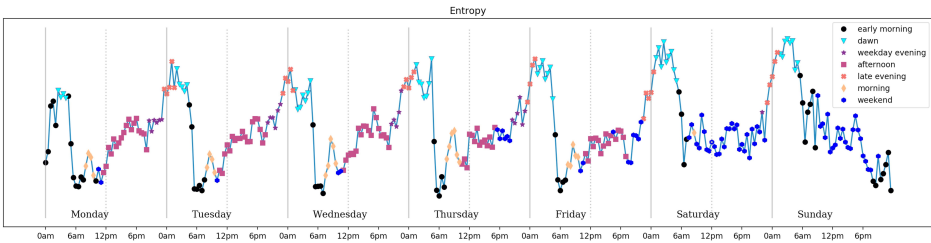
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Time Slice Entropy

$$E(t_k) = - \sum_{i=1}^n p(I(\tau_i, k)) \log p(I(\tau_i, k))$$

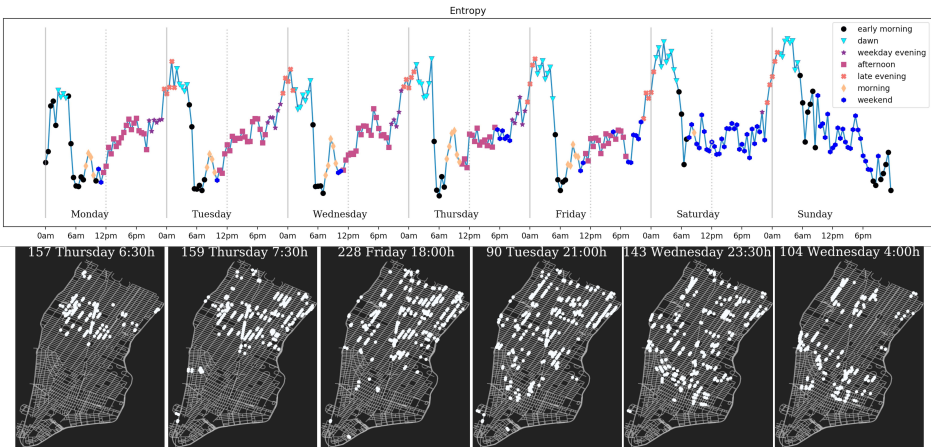
Spatio-Temporal Data Analysis

Analyzing Taxi Pick ups in Downtown Manhattan



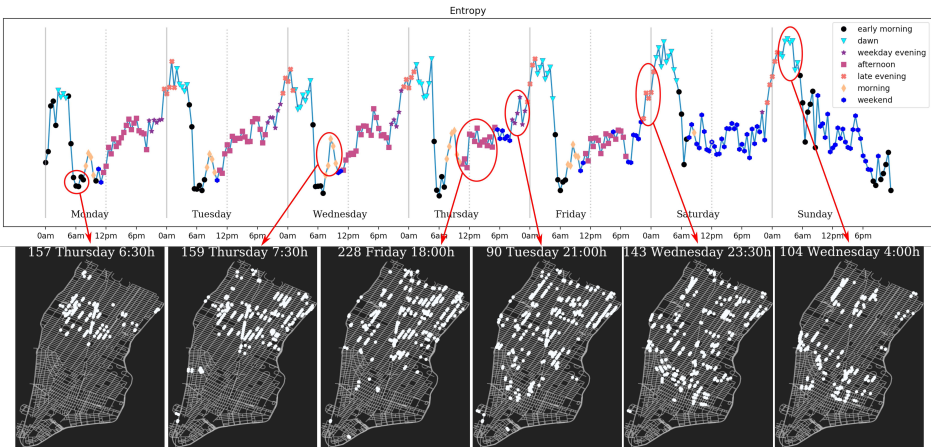
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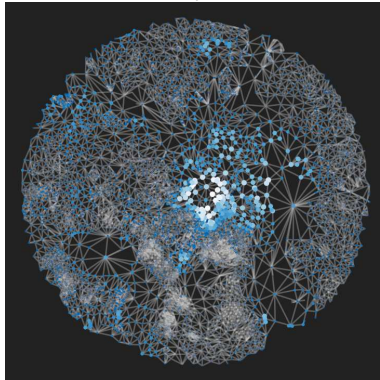
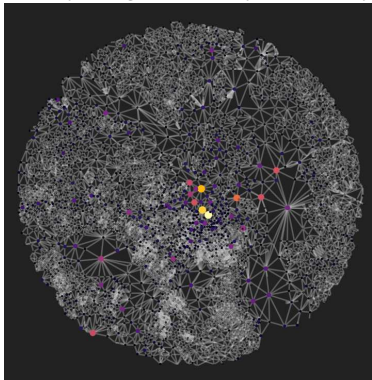
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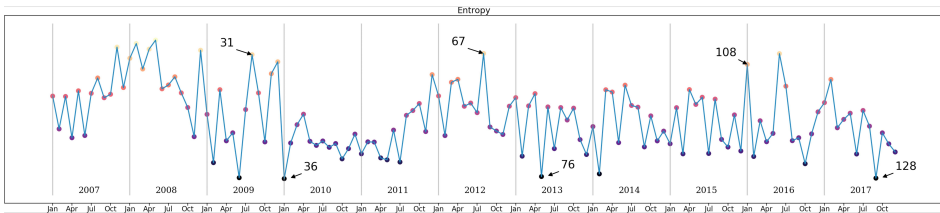
Spatio-Temporal Data Analysis

Analyzing Passerby Robbery in São Paulo City



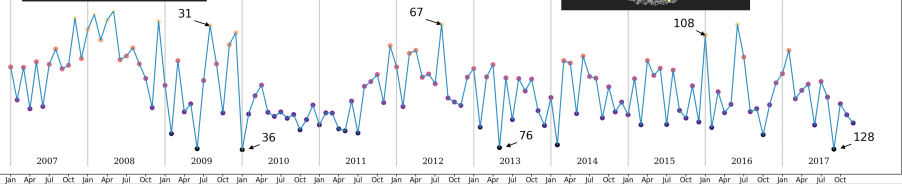
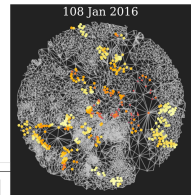
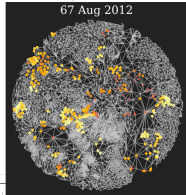
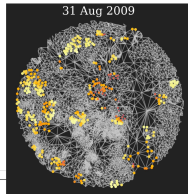
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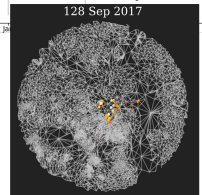
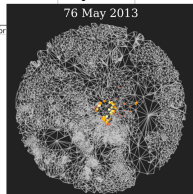
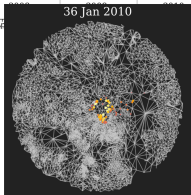
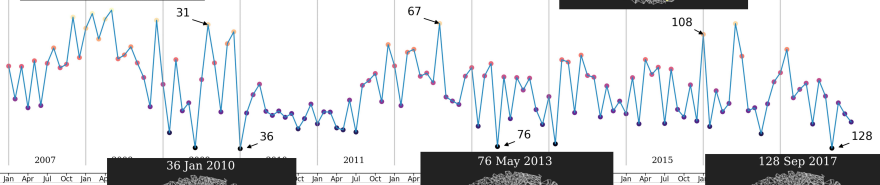
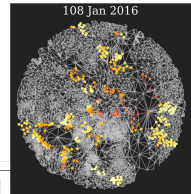
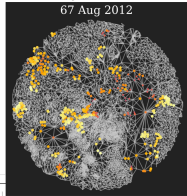
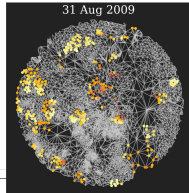
Spatio-Temporal Data Analysis

Analyzing Passerby Robbery in São Paulo City



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Graph Wavelet Transform

Continuous Wavelets Transform

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Moreover, the sought graph wavelet basis must be band pass filters with particular properties.

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The normalizing constant \sqrt{n} ensures that the translation preserves the mean of the signal.

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Notice that $\widehat{f}(s\lambda_l)$ might not be in the range $[0, \lambda_n]$.

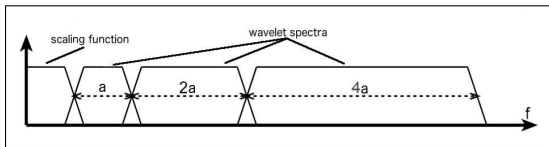
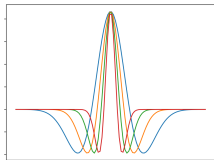
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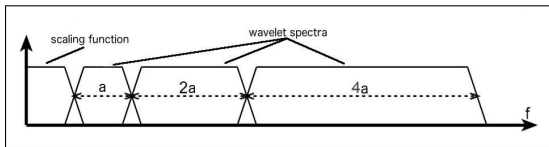
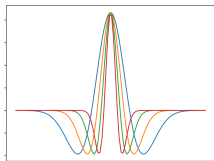
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A complete representation demands to complete the basis with a low-pass scaling function.

Graph Wavelet Transform

Hammond et al. have shown that the following set of filters satisfy the shrink and shift property:

$$g(x) = \begin{cases} x^2 & \text{for } x < 1 \\ -5 + 11x - 6x^2 + x^3 & \text{for } 1 \leq x \leq 2. \\ 4x^{-2} & \text{for } 2 < x \end{cases}$$

and that

$$h(\lambda) = \gamma \exp(-(\frac{10\lambda}{0.3\lambda_n})^4)$$

gives rise to a proper scaling function.

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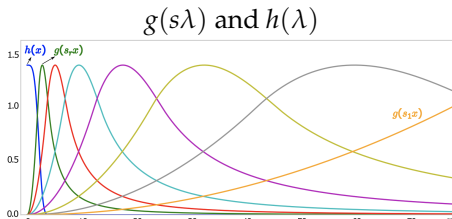
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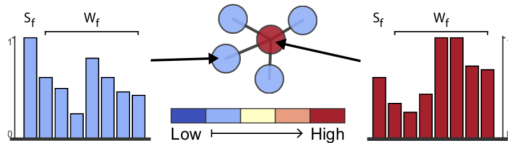
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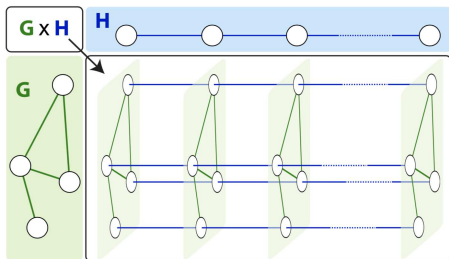
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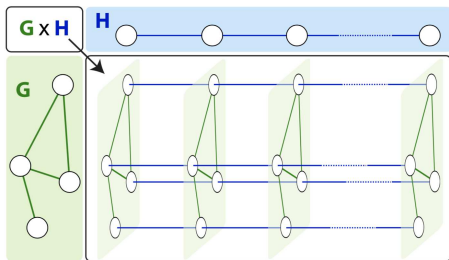


GWT for Spatio-Temporal Data Analysis

Joint Space and Time Analysis



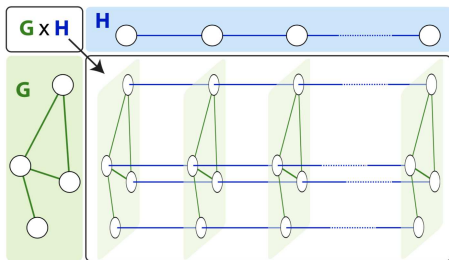
Joint Space and Time Analysis



$$\begin{cases} (u_l, \lambda_l) \text{ eigenpair of } G \\ (v_k, \mu_k) \text{ eigenpair of } H \end{cases} \Rightarrow (u_l \otimes v_k, \lambda_l + \mu_k) \text{ eigenpair of } G \times H$$

where \otimes is the Kronecker product.

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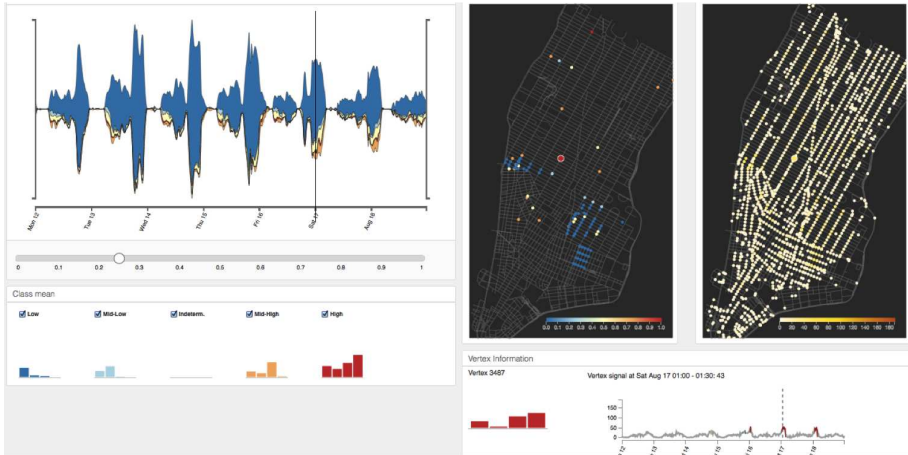


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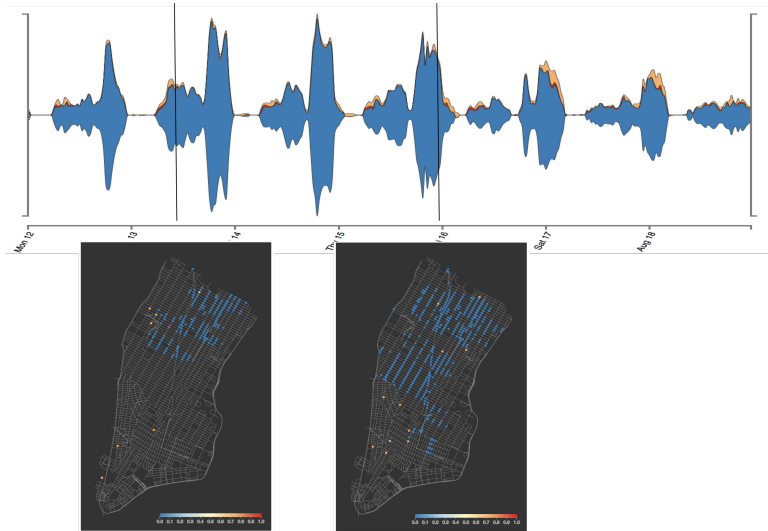
This property is extremely useful to make the joint space and time analysis computationally feasible.

Analyzing taxi pickups

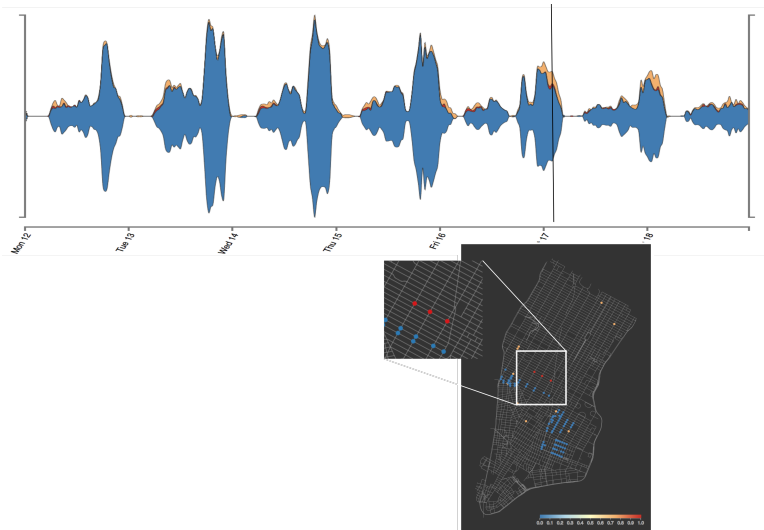


More than 1.5 million nodes and 2 million edges.

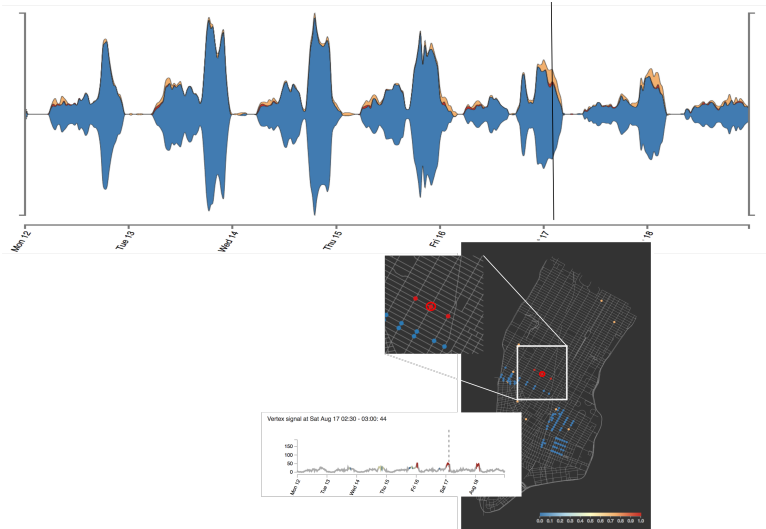
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Conclusions

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 - very hot topic is the interplay between GSP + Deep Learning

THANKS !!